Semi-supervised Learning and Transfer Learning

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Problem formulation of supervised learning.

- Input vector: $oldsymbol{x} = (x_1, x_2, \dots, x_d)^{ op} \in \mathbb{R}^d$
- Output: $y \in \mathbb{R}$

•
$$(\boldsymbol{x}_i, y_i) \stackrel{\text{i.i.d.}}{\sim} p(\boldsymbol{x}, y)$$

- Labeled data: $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$
- Model: $f(\mathbf{x}; \mathbf{w}) = \mathbf{w}^{\top} \mathbf{x}$. (Linear model)

Risk: $R(\boldsymbol{w}) = \iint \operatorname{loss}(y, f(\boldsymbol{x}; \boldsymbol{w}))p(\boldsymbol{x}, y)d\boldsymbol{x}dy$ Empirical Risk: $R_{emp}(\boldsymbol{w}) = \frac{1}{n} \sum_{i=1}^{n} \operatorname{loss}(y_i, f(\boldsymbol{x}_i; \boldsymbol{w}))$ Empirical Risk Minimization (ERM): $\widehat{\boldsymbol{w}} = \operatorname{argmin}_{\boldsymbol{w}} R_{emp}(\boldsymbol{w})$

Semi-Supervised Learning

Problem formulation of semi-supervised learning.

- $(\boldsymbol{x}_i, y_i) \stackrel{\text{i.i.d.}}{\sim} p(\boldsymbol{x}, y)$
- $\mathbf{x}_i \overset{\text{i.i.d.}}{\sim} p(\mathbf{x})$
- Labeled data: $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$
- Unlabeled data: $\{\boldsymbol{x}_{n+1}, \boldsymbol{x}_{n+2}, \dots, \boldsymbol{x}_{n+m}\}$
- Usually $n \ll m$ and n is small
- If *n* is large, it is good to use supervised learning

Semi-supervised learning:

- We have both labeled and unlabeled samples.
- Semi-supervised learning uses both labeled and unlabeled samples.
- The unlabeled samples follow the same distribution of the marginal distribution of p(x, y)

Data generation process

- Input x is generated by a distribution with probability density p(x)
- Output y for x is generated by conditional distribution with probability density p(y|x).

Unlabeled data can be used for capturing p(x)

• input data distribution, input space metric, or better representation.



Semi-supervised learning problem: Learning with labeled and unlabeled data

We have both labeled and unlabeled instances (samples):

- Labeled data: $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$
- Unlabeled data: $\{\boldsymbol{x}_{n+1}, \boldsymbol{x}_{n+2}, \dots, \boldsymbol{x}_{n+m}\}$

Estimate a deterministic mapping from \boldsymbol{x} to \boldsymbol{y} .

- Regression
- Classification

- Weighted maximum likelihood estimation
- Graph-based learning
- self-training
- Clustering
- Generative models

Weighted maximum likelihood

The original goal of ML estimation is to maximize:

$$\mathbb{E}_{\mathbf{x},y}[\log p(y|\mathbf{x})] = \iint \log P(y|\mathbf{x};\mathbf{w})p(\mathbf{x})p(y|\mathbf{x})d\mathbf{x}dy,$$
$$\approx \frac{1}{n}\sum_{i=1}^{n}\log(P(y_i|\mathbf{x}_i;\mathbf{w}))$$

where $P(y|\mathbf{x}; \mathbf{w})$ is a model. Each training instance is equally weighted. Note, ML is equivalent to maximize the negative log-likelihood function:

$$L(\boldsymbol{w}) = \log\left(\prod_{i=1}^{n} P(y_i | \boldsymbol{x}_i; \boldsymbol{w})\right)$$
$$\propto \frac{1}{n} \sum_{i=1}^{n} \log(P(y_i | \boldsymbol{x}_i; \boldsymbol{w}))$$

Weighted maximum likelihood

Weighted maximum likelihood:

$$\max_{\boldsymbol{w}} \sum_{i=1}^{n} p(\boldsymbol{x}_{i}) \log(P(y_{i}|\boldsymbol{x}_{i}; \boldsymbol{w}))$$

- Each training data instance is weighted by $p(\mathbf{x}_i)$.
- p(x) is estimated by using unlabeled data.
- Denser areas are largely weighted
- Training a classifier focusing on the dense areas



- Basic idea: construct a graph capturing the intrinsic shape of input space, and make prediction on the graph.
- Assumption: Data lie on a manifold in the feature space
- The graph represent adjacency relationships among data
- K-nearest neighbor graph (e.g., $A_{ij} = 0, 1$)
- Edge-weighted graph with e.g., $A_{ij} = \exp(-\|\mathbf{x}_i \mathbf{x}_j\|_2^2)$



Label propagation

- Basic idea: Adjacent instances tend to have the same label
- Transductive setting (we have test instances)

$$\min_{\boldsymbol{f}\in\mathbb{R}^n} \sum_{i=1}^n (f_i - y_i)^2 + \lambda \sum_{i=1}^{n+m} \sum_{j=1}^{n+m} A_{ij}(f_i - f_j)^2,$$

where $\lambda > 0$ is the regularization parameter.

- 1st term: (squared) loss function to fit to labeled data.
- 2nd term: regularization function to make adjacent nodes to have similar predictions.



Predict if people are infected by some disease

- Test results are known for some people
- infections spread over social networks



Supervised Learning:

- Training $\{(\boldsymbol{x}_i^{\mathrm{tr}}, y_i^{\mathrm{tr}})\}_{i=1}^n \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\boldsymbol{x}, y)$
- Test $(\mathbf{x}^{\text{te}}, y^{\text{te}}) \stackrel{\text{i.i.d.}}{\sim} \rho_{\text{te}}(\mathbf{x}, y)$ (Not observed during training)
- $p_{\rm tr} = p_{\rm te}$ (Training and test distributions are same)

Semi-supervised Learning:

- Training $\{(\mathbf{x}_i^{\mathrm{tr}}, y_i^{\mathrm{tr}})\}_{i=1}^n \stackrel{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\mathbf{x}, y), \ \{\mathbf{x}_i^{\mathrm{tr}}\}_{i=n+1}^{n+m} \stackrel{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\mathbf{x}).$
- Test $(\mathbf{x}^{\text{te}}, y^{\text{te}}) \stackrel{\text{i.i.d.}}{\sim} \rho_{\text{te}}(\mathbf{x}, y)$ (Not observed during training)
- $p_{\rm tr} = p_{\rm te}$ (Training and test distributions are same)

If $p_{tr} \neq p_{te}$, supervised method and semi-supervised method do not perform well. A possible answer would be Transfer Learning!

Types of Transfer Learning

Key idea: Reduce generalization error in test data. (not in training data)

Unsupervised transfer learning

• $\{(\mathbf{x}_i^{\mathrm{tr}}, y_i^{\mathrm{tr}})\}_{i=1}^{n_{\mathrm{tr}}} \stackrel{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\mathbf{x}, y),$ • $\{\mathbf{x}_j^{\mathrm{te}}\}_{j=1}^{n_{\mathrm{te}}} \stackrel{\mathrm{i.i.d.}}{\sim} p_{\mathrm{te}}(\mathbf{x}), n_{\mathrm{tr}} \ll n_{\mathrm{te}}$

Supervised transfer learning

• $\{(\boldsymbol{x}_{i}^{\mathrm{tr}}, y_{i}^{\mathrm{tr}})\}_{i=1}^{n_{\mathrm{tr}}} \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\boldsymbol{x}, \boldsymbol{y})$ • $\{(\boldsymbol{x}_{i}^{\mathrm{te}}, y_{i}^{\mathrm{te}})\}_{i=1}^{n_{\mathrm{te}}} \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{te}}(\boldsymbol{x}, \boldsymbol{y}), n_{\mathrm{te}} \ll n_{\mathrm{tr}}$

Semi-supervised transfer learning

•
$$\{(\boldsymbol{x}_i^{\mathrm{tr}}, y_i^{\mathrm{tr}})\}_{i=1}^{n_{\mathrm{tr}}} \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\boldsymbol{x}, y)$$

•
$$\{(\mathbf{x}_j^{\text{te}}, y_j^{\text{te}})\}_{j=1}^{n_{\text{te}}} \overset{\text{i.i.d.}}{\sim} p_{\text{te}}(\mathbf{x}, y), n_{\text{te}} \ll n_{\text{tr}}$$

•
$$\{\mathbf{x}_{j}^{\text{te}}\}_{j=n_{\text{te}}+1}^{n_{\text{te}}+n_{\text{te}}'} \stackrel{\text{i.i.d.}}{\sim} p_{\text{te}}(\mathbf{x}), n_{\text{tr}} \ll n_{\text{te}}$$

Key idea: We assume

- It does not need to have test label
- Need some assumption

Standard approaches

- Importance weighted method (e.g., Covariate shift adaptation)
- Subspace based method.

Unsupervised Transfer Learning: Covariate shift adaptation

Problem setup:

- $\{(\boldsymbol{x}_{i}^{\mathrm{tr}}, y_{i}^{\mathrm{tr}})\}_{i=1}^{n_{\mathrm{tr}}} \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\boldsymbol{x}, y),$
- $\{\mathbf{x}_{j}^{\mathrm{te}}\}_{j=1}^{n_{\mathrm{te}}} \stackrel{\mathrm{i.i.d.}}{\sim} p_{\mathrm{te}}(\mathbf{x}), n_{\mathrm{tr}} \ll n_{\mathrm{te}}$

Key idea: Learning a function so that error in test data is minimized under the assumption $p_{tr}(y|\mathbf{x}) = p_{te}(y|\mathbf{x})$



The risk can be written as

$$J(\mathbf{w}) = \iint L(y, f(\mathbf{x})) p_{te}(\mathbf{x}, y) d\mathbf{x} dy$$

=
$$\iint L(y, f(\mathbf{x})) \frac{p_{te}(\mathbf{x}, y)}{p_{tr}(\mathbf{x}, y)} p_{tr}(\mathbf{x}, y) d\mathbf{x} dy$$

=
$$\iint L(y, f(\mathbf{x})) \frac{p_{te}(y|\mathbf{x}) p_{te}(\mathbf{x})}{p_{tr}(y|\mathbf{x}) p_{tr}(\mathbf{x})} p_{tr}(y, \mathbf{x}) d\mathbf{x} dy$$

=
$$\iint L(y, f(\mathbf{x})) \frac{p_{te}(\mathbf{x})}{p_{tr}(\mathbf{x})} p_{tr}(y, \mathbf{x}) d\mathbf{x} dy$$

$$\approx \frac{1}{n_{tr}} \sum_{i=1}^{n_{tr}} L(y_i^{tr}, f(\mathbf{x}_i^{tr})) \frac{p_{te}(\mathbf{x}_i^{tr})}{p_{tr}(\mathbf{x}_i^{tr})}$$

Actually, it is a weighted maximum likelihood problem. Note $\frac{p_{te}(\mathbf{x}_i^{tr})}{p_{tr}(\mathbf{x}_i^{tr})}$ is a ratio of probability densities (density-ratio)

Exponentially-flattened Importance weighted empirical risk minimization (IW-ERM):

$$\min_{f \in \mathcal{F}} \quad \frac{1}{n_{\text{tr}}} \sum_{i=1}^{n_{\text{tr}}} L(y_i^{\text{tr}}, f(\boldsymbol{x}_i^{\text{tr}})) \left(\frac{p_{\text{te}}(\boldsymbol{x}_i^{\text{tr}})}{p_{\text{tr}}(\boldsymbol{x}_i^{\text{tr}})}\right)^{\tau}$$

where $0 \leq \tau \leq 1$ is a tuning parameter for stabilizing the covariate shift adaptation.

- $\tau = 0 \rightarrow \text{ERM}$
- $0 < \tau < 1 \rightarrow$ Intermediate
- $\tau = 1$ IW-ERM

Setting τ to $0 < \tau < 1$ is practically useful.

Unsupervised Transfer Learning: Covariate shift adaptation

Relative Importance weighted empirical risk minimization (RIW-ERM):

$$\min_{f \in \mathcal{F}} \frac{1}{n_{\rm tr}} \sum_{i=1}^{n_{\rm tr}} L(y_i^{\rm tr}, f(\boldsymbol{x}_i^{\rm tr})) \frac{p_{\rm te}(\boldsymbol{x}_i^{\rm tr})}{(1-\alpha)p_{\rm te}(\boldsymbol{x}_i^{\rm tr}) + \alpha p_{\rm tr}(\boldsymbol{x}_i^{\rm tr})}$$

where $0 \le \tau \le 1$ is a tuning parameter for stabilizing the covariate shift adaptation.

- $\alpha = \mathbf{0} \rightarrow \mathsf{ERM}$
- $\bullet \ \mathbf{0} < \alpha < \mathbf{1} \rightarrow \mathsf{Intermediate}$
- $\alpha = 1$ IW-ERM

$$r_{lpha}(oldsymbol{x}) = rac{oldsymbol{p}_{ ext{te}}(oldsymbol{x})}{(1-lpha)oldsymbol{p}_{ ext{tr}}(oldsymbol{x}) + lphaoldsymbol{p}_{ ext{tr}}(oldsymbol{x})} < rac{1}{1-lpha}$$

The density ratio is bounded above by $1/(1-\alpha)$.

Unsupervised Transfer Learning: Importance Weighted Least Squares

The importance weighted least squares problem can be written as

$$\min_{\boldsymbol{w}} J(\boldsymbol{w}) = \frac{1}{n_{\mathrm{tr}}} \sum_{i=1}^{n_{\mathrm{tr}}} r(\boldsymbol{x}_i^{\mathrm{tr}}) \| y_i^{\mathrm{tr}} - \boldsymbol{w}^\top \boldsymbol{x}_i^{\mathrm{tr}} \|_2^2,$$

where $r(\mathbf{x})$ is a weight function (e.g., density-ratio).

Take the derivative w.r.t. \boldsymbol{w} and equating it to zero.

$$\frac{\partial J(\boldsymbol{w})}{\partial \boldsymbol{w}} = -\frac{2}{n_{\mathrm{tr}}} \sum_{i=1}^{n_{\mathrm{tr}}} r(\boldsymbol{x}_i^{\mathrm{tr}}) (y_i^{\mathrm{tr}} - \boldsymbol{w}^\top \boldsymbol{x}_i^{\mathrm{tr}}) \boldsymbol{x}_i^{\mathrm{tr}} = \boldsymbol{0}$$
$$\widehat{\boldsymbol{w}} = \left(\sum_{i=1}^{n_{\mathrm{tr}}} r(\boldsymbol{x}_i^{\mathrm{tr}}) \boldsymbol{x}_i^{\mathrm{tr}} \boldsymbol{x}_i^{\mathrm{tr}}^\top\right)^{-1} \sum_{i=1}^{n_{\mathrm{tr}}} r(\boldsymbol{x}_i^{\mathrm{tr}}) y_i^{\mathrm{tr}} \boldsymbol{x}_i^{\mathrm{tr}}$$

Comparison of EIW-LS and RIW-LS:



Problem formulation:

- $\{(\boldsymbol{x}_{i}^{\mathrm{tr}}, y_{i}^{\mathrm{tr}})\}_{i=1}^{n_{\mathrm{tr}}} \overset{\mathrm{i.i.d.}}{\sim} p_{\mathrm{tr}}(\boldsymbol{x}, y)$
- $\{(\mathbf{x}_{j}^{\text{te}}, y_{j}^{\text{te}})\}_{j=1}^{n_{\text{te}}} \stackrel{\text{i.i.d.}}{\sim} p_{\text{te}}(\mathbf{x}, y), n_{\text{te}} \ll n_{\text{tr}}$

We assume to have a large number of training samples and a small number of paired target labeled samples.

- Frustratingly easy domain adaptation
- Multi-task Learning
- Fine-tuning (Deep Learning)

Naive approach: Pooling training and test samples

$$\begin{split} J(\boldsymbol{w}) &= \iint \mathsf{loss}(y, f(\boldsymbol{x}; \boldsymbol{w})) p_{\mathrm{te}}(\boldsymbol{x}, \boldsymbol{y}) \mathsf{d} \boldsymbol{x} \mathsf{d} \boldsymbol{y} \\ &= \alpha \iint \mathsf{loss}(y, f(\boldsymbol{x}; \boldsymbol{w})) p_{\mathrm{tr}}(\boldsymbol{x}, \boldsymbol{y}) \mathsf{d} \boldsymbol{x} \mathsf{d} \boldsymbol{y} \\ &+ (1 - \alpha) \iint \mathsf{loss}(y, f(\boldsymbol{x}; \boldsymbol{w})) p_{\mathrm{te}}(\boldsymbol{x}, \boldsymbol{y}) \mathsf{d} \boldsymbol{x} \mathsf{d} \boldsymbol{y} \\ &\simeq \frac{\alpha}{n_{\mathrm{tr}}} \sum_{i=1}^{n_{\mathrm{tr}}} \mathsf{loss}(y_i^{\mathrm{tr}}, f(\boldsymbol{x}_i^{\mathrm{tr}}; \boldsymbol{w})) + \frac{(1 - \alpha)}{n_{\mathrm{te}}} \sum_{j=1}^{n_{\mathrm{te}}} \mathsf{loss}(y_j^{\mathrm{te}}, f(\boldsymbol{x}_j^{\mathrm{te}}; \boldsymbol{w})), \end{split}$$

where 0 $\leq \alpha \leq$ 1 is a tuning parameter to control trade off between source and target errors.

Supervised Transfer Learning: Multi-task Learning

Problem formulation:

- Task1:{ $(x_i^{(1)}, y_i^{(1)})$ } $_{i=1}^{n_1} \stackrel{\text{i.i.d.}}{\sim} p_1(x, y)$
- Task2: $\{(x_j^{(2)}, y_j^{(2)})\}_{j=1}^{n_2} \overset{\text{i.i.d.}}{\sim} p_2(x, y)$

• ...

- TaskM: { $(\boldsymbol{x}_{j}^{(M)}, y_{j}^{(M)})$ } $_{j=1}^{n_{M}} \stackrel{\text{i.i.d.}}{\sim} p_{M}(\boldsymbol{x}, y)$
- Linear Models: $f_1(\mathbf{x}^{(1)}) = \mathbf{w}_1^{\top} \mathbf{x}^{(1)}, f_2(\mathbf{x}^{(2)}) = \mathbf{w}_2^{\top} \mathbf{x}^{(2)}, \dots, f_M(\mathbf{x}^{(M)}) = \mathbf{w}_M^{\top} \mathbf{x}^{(M)}$

$$\min_{\boldsymbol{w}_1,\ldots,\boldsymbol{w}_M} \sum_{m=1}^M \frac{1}{n_m} \sum_{i=1}^{n_m} \operatorname{loss}(y_i^{(m)}, f_m(\boldsymbol{x}^{(m)})) + \lambda R(\boldsymbol{w}_1,\ldots,\boldsymbol{w}_M).$$

where $R(\boldsymbol{w}_1, \ldots, \boldsymbol{w}_M)$ is a regularizer.

- $\lambda = 0$: Independently optimize **w**s
- $\lambda > 0$: We share some information among models.

Semi-supervised Learning

Multi-task learning optimization (Graph-Laplacian).

$$\min_{\boldsymbol{w}_{1},...,\boldsymbol{w}_{M}} \sum_{m=1}^{M} \frac{1}{n_{m}} \sum_{i=1}^{n_{m}} \operatorname{loss}(y_{i}^{(m)}, f_{m}(\boldsymbol{x}_{i}^{(m)})) + \lambda \sum_{m=1}^{M} \sum_{m'=1}^{M} r_{m,m'} \|\boldsymbol{w}_{m} - \boldsymbol{w}_{m'}\|_{2}^{2}.$$

where $r_{m,m'} \ge 0$ is a model parameter (similarity between models). If $r_{m,m'} > 0$, we make w_m and $w_{m'}$ close.

Supervised Transfer Learning: Multi-task Learning

Other approach: Explicitly including shared parameter. We decompose $w_m = w_0 + v_m$ That is

• $f_1(\mathbf{x}^{(1)}) = (\mathbf{w}_0 + \mathbf{v}_1)^\top \mathbf{x}^{(1)}$, • $f_2(\mathbf{x}^{(2)}) = (\mathbf{w}_0 + \mathbf{v}_2)^\top \mathbf{x}^{(2)}$,

•
$$f_M(x^{(M)}) = (w_0 + v_M)^\top x^{(M)}$$

where \boldsymbol{w}_0 is a common factor for all models.

For squared-loss, we can write the problem as

$$\min_{\boldsymbol{w}_{1},...,\boldsymbol{w}_{M}} \frac{1}{2} \sum_{m=1}^{M} \frac{1}{n_{m}} \sum_{i=1}^{n_{m}} \left(y_{i}^{(m)} - (\boldsymbol{w}_{0} + \boldsymbol{v}_{m})^{\top} \boldsymbol{x}_{i}^{(m)} \right)^{2} + \lambda (\|\boldsymbol{w}_{0}\|_{2}^{2} + \sum_{m=1}^{M} \|\boldsymbol{v}_{m}\|_{2}^{2})$$

Supervised Transfer Learning: Frustratingly easy domain adaptation

A frustratingly easy feature augmentation approach:

$$egin{aligned} oldsymbol{z}^{ ext{tr}} &= (oldsymbol{x}^{ ext{tr}}^ op oldsymbol{b} \mathbf{x}^{ ext{tr}}^ op oldsymbol{0}_{ ext{d}}^ op)^ op, \ oldsymbol{z}^{ ext{te}} &= (oldsymbol{x}^{ ext{te}}^ op oldsymbol{0}_{ ext{d}}^ op oldsymbol{x}^{ ext{te}}^ op)^ op, \end{aligned}$$

The inner product of z in the same domain is give as

$$egin{aligned} & oldsymbol{z}^{\mathrm{tr}^{ op}}oldsymbol{z}^{\mathrm{tr}} &= 2oldsymbol{x}^{\mathrm{tr}^{ op}}oldsymbol{x}^{\mathrm{tr}}, \ & oldsymbol{z}^{\mathrm{te}^{ op}}oldsymbol{z}^{\mathrm{te}^{ op}} &= 2oldsymbol{x}^{\mathrm{te}^{ op}}oldsymbol{x}^{\mathrm{te}}, \end{aligned}$$

while we have

$$\boldsymbol{z}^{\mathrm{tr}^{\top}}\boldsymbol{z}^{\mathrm{te}} = \boldsymbol{x}^{\mathrm{tr}^{\top}}\boldsymbol{x}^{\mathrm{tr}},$$

Then, we train a supervised learning method with the transformed vectors *z*. Super easy!!!!

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Actually, supervised transfer learning can be regarded as a two-task learning problem. First task is for training and second task is for test. Let us denote the transformed vectors as

$$egin{aligned} oldsymbol{z}^{ ext{tr}} &= (oldsymbol{x}^{ ext{tr}}^ op oldsymbol{x}^{ ext{tr}}^ op oldsymbol{0}_{ ext{d}}^ op)^ op \in \mathbb{R}^{3d}, \ oldsymbol{z}^{ ext{te}} &= (oldsymbol{x}^{ ext{te}}^ op oldsymbol{0}_{ ext{d}}^ op oldsymbol{x}^{ ext{te}}^ op)^ op \in \mathbb{R}^{3d}, \end{aligned}$$

where $\mathbf{0}_{d} \in \mathbb{R}^{d}$ is the vector whose elements are all zero. And, we consider a linear regression problem: The model parameter of the linear model can be written as

$$oldsymbol{w} = (oldsymbol{w}_0^ op oldsymbol{v}_1^ op oldsymbol{v}_2^ op)^ op \in \mathbb{R}^{3d}$$

Supervised Transfer Learning: Multi-task Learning

$$J(\boldsymbol{w}) = \frac{1}{2n_{\rm tr}} \sum_{i=1}^{n_{\rm tr}} \|y_i^{\rm tr} - \boldsymbol{z}_i^{\rm tr}^{\top} \boldsymbol{w}\|_2^2 + \frac{1}{2n_{\rm te}} \sum_{i=1}^{n_{\rm te}} \|y_i^{\rm te} - \boldsymbol{z}_i^{\rm te}^{\top} \boldsymbol{w}\|_2^2 + \lambda \|\boldsymbol{w}\|_2^2$$
$$= \frac{1}{2} \sum_{m=1}^{M} \frac{1}{n_m} \sum_{i=1}^{n_m} \left(y_i^{(m)} - (\boldsymbol{w}_0 + \boldsymbol{v}_m)^{\top} \boldsymbol{x}_i^{(m)} \right)^2 + \lambda (\|\boldsymbol{w}_0\|_2^2 + \sum_{m=1}^{M} \|\boldsymbol{v}_m\|_2^2),$$

where we use

$$\begin{split} \boldsymbol{w}^{\top} \boldsymbol{z}^{\text{tr}} &= (\boldsymbol{w}_0 + \boldsymbol{v}_1)^{\top} \boldsymbol{x}^{\text{tr}}, \quad \boldsymbol{w}^{\top} \boldsymbol{z}^{\text{te}} = (\boldsymbol{w}_0 + \boldsymbol{v}_2)^{\top} \boldsymbol{x}^{\text{te}} \\ \boldsymbol{x}^{\text{tr}} &= \boldsymbol{x}^{(1)}, \quad \boldsymbol{x}^{\text{te}} = \boldsymbol{x}^{(2)}, \\ \|\boldsymbol{w}\|_2^2 &= \|\boldsymbol{w}_0\|_2^2 + \sum_{m=1}^2 \|\boldsymbol{v}_m\|_2^2. \end{split}$$

Frustratingly easy domain adaptation is a multi-task learning.

Semi-supervised Learning

- Semi-supervised learning. Use unlabeled samples and assume the data distribution of unlabeled data is same as training.
- Weighted Maximum Likelihood, Graph-based method.
- Transfer Learning. Use samples from test data. Training and test distributions are different.
- Covariate shift adaptation, frustratingly easy domain adaptation.